Name of the module/subject Code Mobile machinery gears and drives Code Mobile machinery gears and drives Profile of study 10106141610106144 Field of study Profile of study Year /Semester Mechanika i budowa maszyn (brak) 3 Elective path/specialty Subject offered in: Maszyny robocze Course (compulsory, ele obligatory Cycle of study: First-cycle studies Form of study (full-time,part-time) Course (compulsory, ele obligatory No. of hours Form of study (full-time,part-time) No. of credits Lecture: 16 Classes: - Laboratory: 8 Project/seminars: 4 Status of the course in the study program (Basic, major, other) (university-wide, from another field) (brak) Education areas and fields of science and art ECTS distribution (number)			
Mechanika i budowa maszyn (general academic, practical) (brak) 3 Elective path/specialty Subject offered in: Maszyny robocze Course (compulsory, ele obligatory Year Polish obligatory Cycle of study: Form of study (full-time,part-time) First-cycle studies part-time No. of hours Lecture: 16 Classes: - Laboratory: 8 Project/seminars: - 4 Status of the course in the study program (Basic, major, other) (university-wide, from another field) (brak) Education areas and fields of science and art ECTS distribution (numl			
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Education areas and fields of science and art ECTS distribution (numl			
and %)			
technical sciences 4 100%			
Responsible for subject / lecturer:			
dr inż. Damian Frąckowiak email: damian.frackowiak@put.poznan.pl tel. 48 61 2244516 Faculty of Working Machines and Transportation ul. Piotrowo 3 60-965 Poznań			
Prerequisites in terms of knowledge, skills and social competencies:			
1 Knowledge The knowledge gained in the field of the hydraulic and pneumatic actuators. Basic knowledge of the basics of machine design, theory of machines.			
Skills Skills acquired in the courses: hydraulic and pneumatic actuators, basics of machine design. Ability to solve problems in the field of fluid mechanics, automation and mechanics.			
3 Social Understanding the need to expand their competence, willingness to work together as a team			
Assumptions and objectives of the course:			
Understanding the structure of the propulsion systems of self-propelled working machines, types, construction and characteristics of the drives and methods of their control. Examination and computer simulation of selected hydrostatic drives used in working machines.			
Study outcomes and reference to the educational results for a field of study			
Knowledge:			
1. Knows the construction and function of hydraulic and electric propulsion systems used in working machines [K1A_W16] 2. Knows design methods of selected hydrostatic propulsion systems [K1A_W17]			
3. Knows programs aiding the design and analysis of the work of hydrostatic propulsion systems [K1A_W24]			
Skills:			
1. Is able to describe the basic drive systems used in working machines - [K1A_U09]			
2. Is able to design selected hydrostatic drive systems - [-]			
3. Is able to build and analyze selected systems used in drives of working machines - [K1A_U19]			
Social competencies:			
1. Understands the need and knows the possibilities of lifelong learning - [K1A_K01]			
2. Is aware of and understands the importance and impact of non-technical aspects of mechanical engineering activities and its impact on the environment and responsibility for own decisions [K1A_K02]			
3. Has a sense of responsibility for one?s own work and is willing to comply with the principles of teamwork and taking responsibility for collaborative tasks [K1A_K04]			

Assessment methods of study outcomes

- Written exam of the course.

- Assessment of laboratory exercises based on assessments of the reports and short entrance tests.

Course description

Classification of propulsion systems Types and construction of the main drives, auxiliary drives, examples of construction. Hydrostatic transmissions in wheeled and tracked machines, examples and solutions. Hydraulic actuators, hydraulic tools in tractors. Hydraulic steering servomechanisms. Monitoring and control of hydrostatic drives, "load sensing" (LS) and LUDV control systems, hydraulic drives with programmable microprocessor control. Analysis of exemplary drive systems for wheeled and tracked machines. Propulsion systems with DC and AC motors. Control and speed regulation of electric motors, braking, reverse in direction of work. Computer programs for modeling and simulation of hydraulic and electro-hydraulic transmissions, examples of practical applications in relation to traction drives.

Basic bibliography:

1. Szydelski Z.: Pojazdy samochodowe ? napęd i sterowanie hydrauliczne. WKŁ, W-wa, 1999.

2. Osiecki A. : Hydrostatyczny napęd maszyn. WNT, Warszawa 1998.

3. Stryczek S.: Napęd hydrostatyczny. Tom I i II, WNT, Warszawa, 2005.

4. S. Januszewski, A. Pytlak, M. Rosnowska-Nowaczyk; Napęd Elektryczny; WSiP Warszawa 1994

Additional bibliography:

1. Pizoń A.: Elektrohydrauliczne analogowe i cyfrowe układy automatyki. WNT, Warszawa, 1998.

2. Exner H., Freitag R., Geis H., Lang R., Oppolzer J., Schwab P., Sumpf E.: Der Hydraulik Trainer Band 1, Grundlagen und komponenten der fluidtechnik Hydraulik. Mannesmann Rexroth, 1998.

3. J. Kosmol; Elektryczne silniki i układy napędowe obrabiarek i maszyn technologicznych; Wydawnictwo Politechniki Śląskiej; Gliwice 1993.

Result of average student's workload

Activity		Time (working hours)
1. Udział w wykładach		16
2. Utrwalenie treści wykładu		6
3. Konsultacje dotyczące materiału przekazanego na wykładach	2	
4. Przygotowanie do egzaminu	6	
5. Udział w egzaminie	1	
6. Przygotowanie do ćwiczeń laboratoryjnych		6
7. Udział w ćwiczeniach laboratoryjnych		8
8. Konsultacje dotyczące materiału przekazanego na ćwiczeniach laboratoryjnych		2
9. Udział w zaliczeniu		1
Student's wo	orkload	
Source of workload	hours	ECTS
Total workload	60	4
Contact hours	30	2
Practical activities	27	2